Latent-Variable Models A Brief Overview

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Learning goals:

- **1** What are some uses of latent-variable models?
- ² General ideas used to design inference algorithms:
	- \blacktriangleright What is expectation maximization?
	- \blacktriangleright What is variational Bayes?
- **8** What is a variational autoencoder?
	- \blacktriangleright What is amortized inference?
	- \blacktriangleright How can we train them via backpropagation?

Statistical models with latent variables

Fully-observed model

▶ Observe (x, y) and learn $x \rightarrow y$

Latent-variable model

Explain variation in observed x using latent causes z

Use a latent variable model:

Measurements are indirect observations (of an underlying simpler structure)

▶ Capture complicated interactions using a few latent variables and explore high-dimensional data

Generative: \approx probability of x in training data P_x

- \blacktriangleright Draw new samples similar to the training data
- ▶ Get probability of a scenario given the model and detect outliers or surprising inputs

They can be used, for example, to infer missing data, explain complicated relationships with simpler ones, learn the distribution of the training data.

Some types of latent-variable models

Part of Generative Adversarial Networks and Variational Autoencoders (and others)

They can be used, for example, to infer missing data, explain complicated relationships with simpler ones, learn the distribution of the training data.

They encompass a wide variety of problems: filtering, state inference, generative models, unsupervised learning, to name a few examples.

Concrete Example: A generative model with a Gaussian latent space

Gaussian prior on latents $P_z = \mathcal{N}(\mu_z, \Sigma_z)$. ▶ Keep it simple: μ_z =0, Σ_z = I_N

"Decoder" generates mean $\mu_i = [f_{\theta}(z)]_i$ for each x_i

Model *x* as conditionally Gaussian given *z*:
\n
$$
\triangleright P_{x|z}^{\theta} = \mathcal{N}[f_{\theta}(z), \sigma^2 I_M]
$$

Recall

- Aarginal probability: $P_x = \int_{dz} P_{x,z}$
- \blacktriangleright Conditional probability chain rule: $P_{x,z} = P_{x|z}P_z$

$$
\mathsf{P}_{\mathbf{x}}^{\theta} = \int_{dz} \mathsf{P}_{\mathbf{x},z}^{\theta} = \int_{dz} \mathsf{P}_{\mathbf{x}|z}^{\theta} \mathsf{P}_{z}
$$

Excellent: We now have a generative model $P_x \approx P_x^{\theta}$

How do I train a latent variable model?

Given a set of (independent) observations $\mathcal{X} = \{\mathbf{x}_1, ..., \mathbf{x}_L\}$, maximize average log-likelihood

$$
\hat{\boldsymbol{\theta}} \leftarrow \operatorname*{argmax}_{\boldsymbol{\theta}} \langle \ln \mathsf{P}_{\mathbf{x}}^{\boldsymbol{\theta}} \rangle_{\mathbf{x} \in \mathcal{X}}
$$

Easier said than done: We need to integrate $P_x^{\theta} = \int_{dz} P_{x|z}^{\theta} P_z$

 \blacktriangleright This may lack a closed-form solution and be impractical to sample

Many methods for estimating latent states and parameters

- \triangleright Sample from the latent states (and/or unknown parameters)
- ▶ Message-passing: update parts of a larger model based on dependencies between variables
- ▶ More: Bayesian and assumed-density filtering, contrastive learning, Viterbi and dynamic programming

Expectation Maximization

Variational Bayes

Know z and x ? Get θ via supervised learning

Know θ, x, P_z ? Get $\mathsf{P}^{\theta}_{z|x}$ via Bayes' rule

Choose initial θ and iterate:

- ▶ **Expectation:**
	- Given θ , get $\mathsf{P}^{\bm{\theta}}_{\bm{z}|\bm{x}}$
	- Loss $\mathcal{L}_{\bm{\theta}}(\hat{\bm{\theta}})$: average $\ln \mathtt{P}_{\bm{x}|\bm{z}}^{\hat{\bm{\theta}}}$ over $\mathtt{P}_{\bm{z}|\bm{x}}^{\bm{\theta}}$
- ▶ **Maximization:**
	- Adjust $\hat{\boldsymbol{\theta}}$ to maximize $\mathcal{L}_{\boldsymbol{\theta}}(\hat{\boldsymbol{\theta}})$

Converges to local optimum

Calculating $P^{\bm{\theta}}_{\bm{z}|\bm{x}}$ *may be intractable*

Approximate $\mathsf{P}_{\bm{z}|\bm{x}}^{\bm{\theta}}$ with simpler $\mathrm{Q}_{\bm{z}|\bm{x}}^{\bm{\phi}}$ (parameters $\bm{\phi}$)

Adjust ϕ to maximize Evidence Lower Bound (ELBO)

$$
\mathcal{L}(\theta, \phi) := \big\langle \ln \mathrm{P}^\theta_{x|z} \big\rangle_{\mathrm{Q}^\phi_{z|x}} + \big\langle \ln \mathrm{P}_z \big\rangle_{\mathrm{Q}^\theta_{z|x}} + \mathrm{H} \big[\mathrm{Q}^\phi_{z|x} \big]
$$

- \blacktriangleright $\langle \ln P_{x}^{\theta}|_{z}\rangle_{\mathbf{Q}}$: Choose z consistent with x
- \blacktriangleright $\langle \ln \mathsf{P}_z \rangle_{\mathbf{Q}}$: Keep $\mathrm{Q}^{\boldsymbol{\phi}}_{z|\boldsymbol{x}}$ close to prior
- \blacktriangleright **H**[$Q_{z|x}^{\phi}$]**:** Maximize entropy

In the Homework:

- ▶ Show: $\mathcal{L}(\theta, \phi) \leq \ln P_x^{\theta}$
- ▶ Show: maximizing $\mathcal{L}(\theta, \phi)$ in $\phi \rightarrow$ tighter bound

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They encompass a wide variety of problems: filtering, state inference, generative models, unsupervised learning, to name a few examples.

It can be hard to directly optimize the likelihood of a latent variable model. There are many inference approaches and approximations.

Expectation maximization and variational Bayes try to approximate the maximum-likelihood parameters while learning distributions over latent states.

The "variational" in variational autoencoders comes from the fact that we use variational Bayes to train them. Where does the "autoencoder" come from?

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Amortized inference:

- \blacktriangleright Predict $\phi_{z|x} = {\mu_{z|x}, \sigma_{z|x}}$ from x
	- Train neural network to map $g: x \to \phi$
- \blacktriangleright Evaluate $\ln \mathsf{P}^{\bm{\theta}}_{\bm{x}| \bm{z}}$
	- Sample $z \leftarrow \xi \sigma_{\boldsymbol{z}|\boldsymbol{x}}$ + $\boldsymbol{\mu}_{\boldsymbol{z}|\boldsymbol{x}}$ where $\xi \sim \mathcal{N}[0, I_N]$
	- Compute $\ln \mathsf{P}^{\bm{\theta}}_{\bm{x}|\bm{z}}$
- \blacktriangleright How can I train this?! It is stochastic?

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Reparameterization trick:

- ▶ Freeze ξ : no more random quantities
- ▶ Backpropagation:
	- Tune f_{θ} to increase log-likelihood
	- \blacksquare Tune g_{θ} to improve $\phi_{z|x}$

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Use stochastic gradient descent (and many tricks)

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Expectation maximization and variational Bayes learn and approximate maximum-likelihood parameters while learning distributions over latent states

Variational autoencoders are a type of deep latent-variable model that maps latent states to observations using a decoding network, and computes approximate distributions over latent states using an encoding network

Appendix

"Zero-Shot Text-to-Image Generation" Ramesh et al. (2021) openai.com/blog/dall-e

Example: Gaussian mixture model

- $\blacktriangleright\,$ E: Get Pr that \boldsymbol{x} comes from each cluster
- $▶$ **M**: Use as weights to update μ , Σ for all clusters